



# MagTrack: Enabling Safe Driving Monitoring Based on Wearable Magnetic Sensing

**Hua Huang**, Hongkai Chen, and Shan Lin



# Annual Distracted Driving Statistics



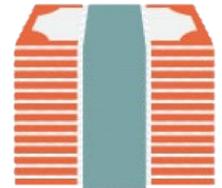
**Texting while driving:  
6X danger than drunk  
driving**

**1.5M crashes**



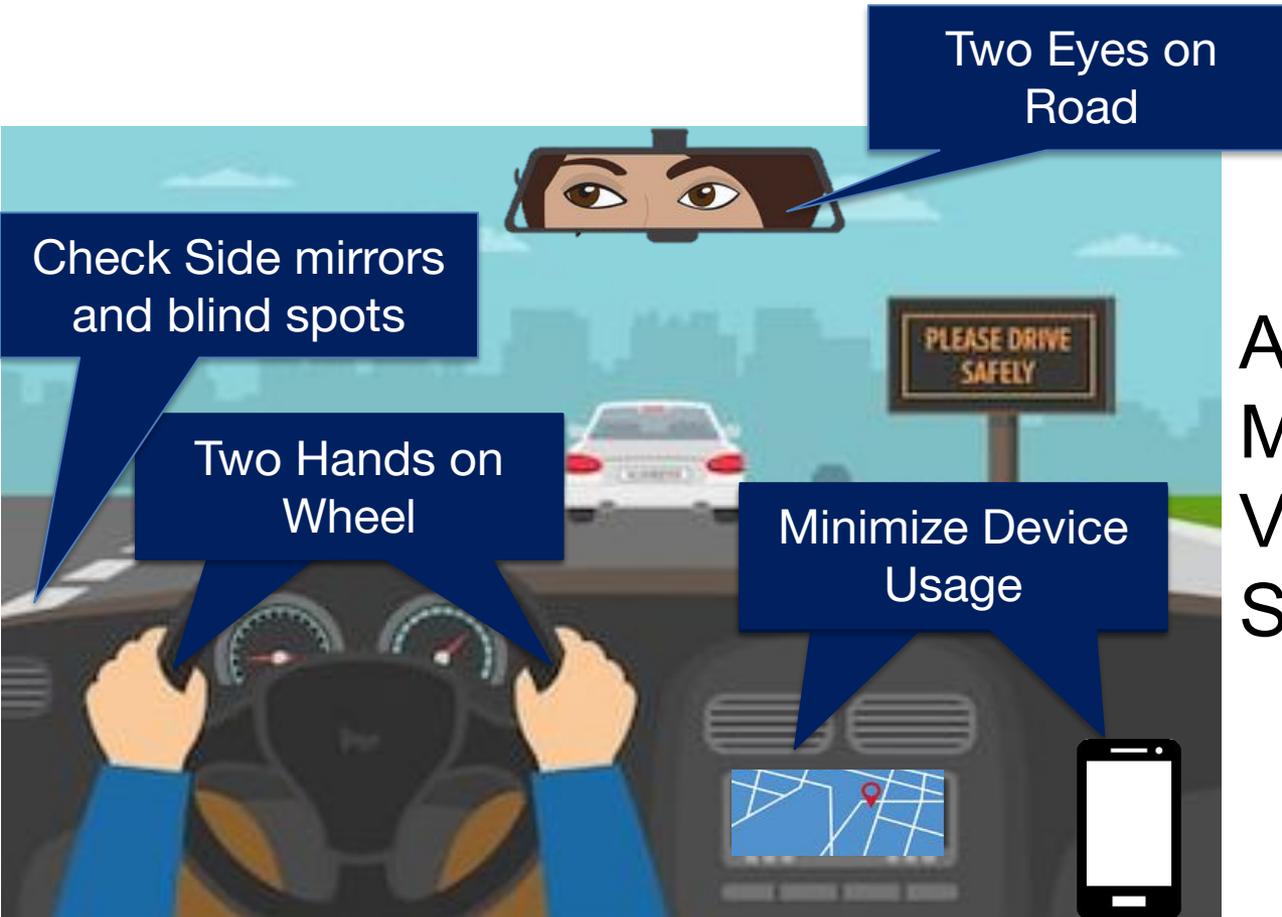
**3K+ deaths**

**\$129B financial loss**





# Safe Driving Guidelines



Avoid:  
Manual Distraction  
Visual Distraction  
Safe Steering



## Car Motion Monitor\*

- Can't detect dangerous driver gestures



Snapshot from progressive auto insurance

\*Chen. et.al “Invisible Sensing of Vehicle Steering with Smartphones”



## Wearable IMU Systems\*

- multiple active sensors needed



Driver Alert System



Smartwatches

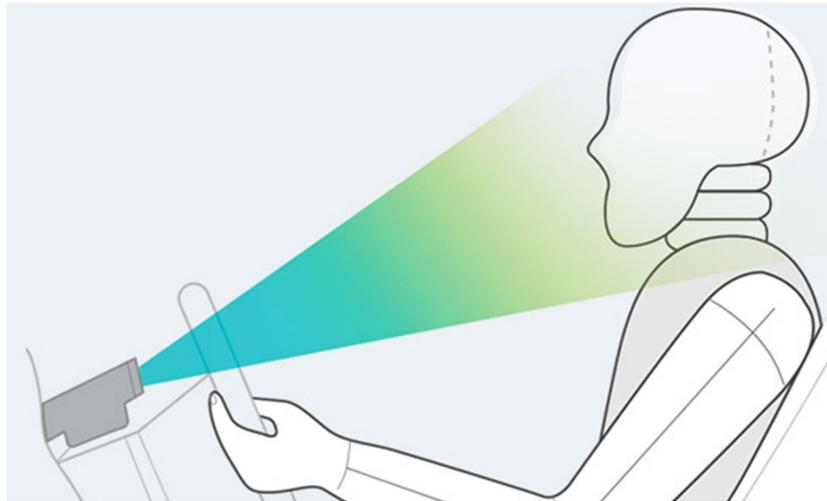
\*Bi et. al. "SafeWatch: A Wearable Hand Motion Tracking System for Improving Driving Safety"

\*Karatas et al. "Leveraging wearables for steering and driver tracking"



## Camera Systems\*

- Influenced by ambient lighting conditions



\*You et al. “Carsafe app: Alerting drowsy and distracted drivers using dual cameras on smartphones”



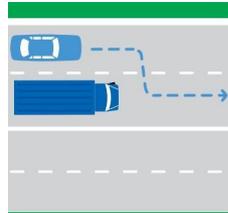
- Monitor multiple targets with single device
  - Solution: Magnetic sensing
  - ❖ Magnetic tags to provide additional signals
  - ❖ Simultaneous tracking and classification for multiple tags
- Additional challenges
  - Posture variations
  - Environmental magnetic field
  - Energy constraints



# MagTrack Overview



## Safe Driving Apps



**Safe Lane Change/Turn**



**Manual Distraction**



**Visual Distraction**



**Bimanual Steering**

## Smartwatch

**Simultaneous Hands and Head Tracking and Classification**

## Magnetic Wearables



**One hand wearable**



**One head wearable**



# Wearable Magnetics Design



- Low-cost, battery-free and compatible with existing accessories
- Works at night. Line-of-sight not needed.
- Precise tracking, handles orientation changes





# Hand and Head Tracking with Wearable Magnetics



# Challenge: Insufficient Sensing Channels

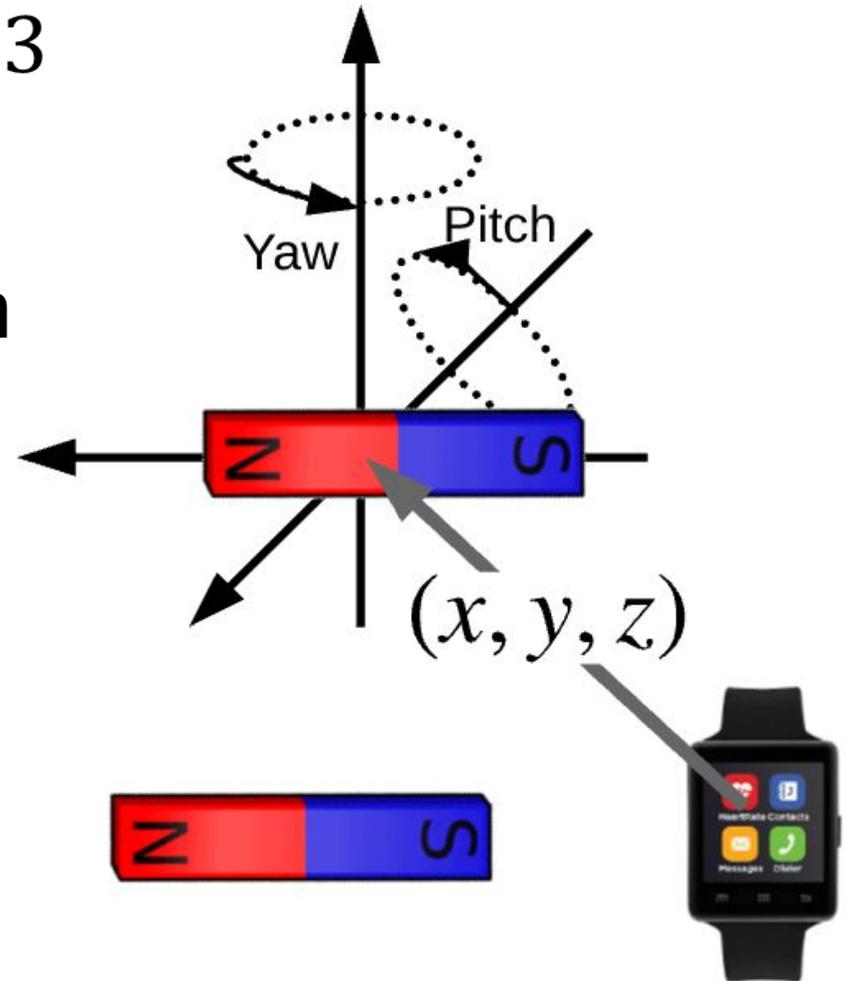


# of measurements:  $n = 3$

# of variables:  $m = 5 \times 2$

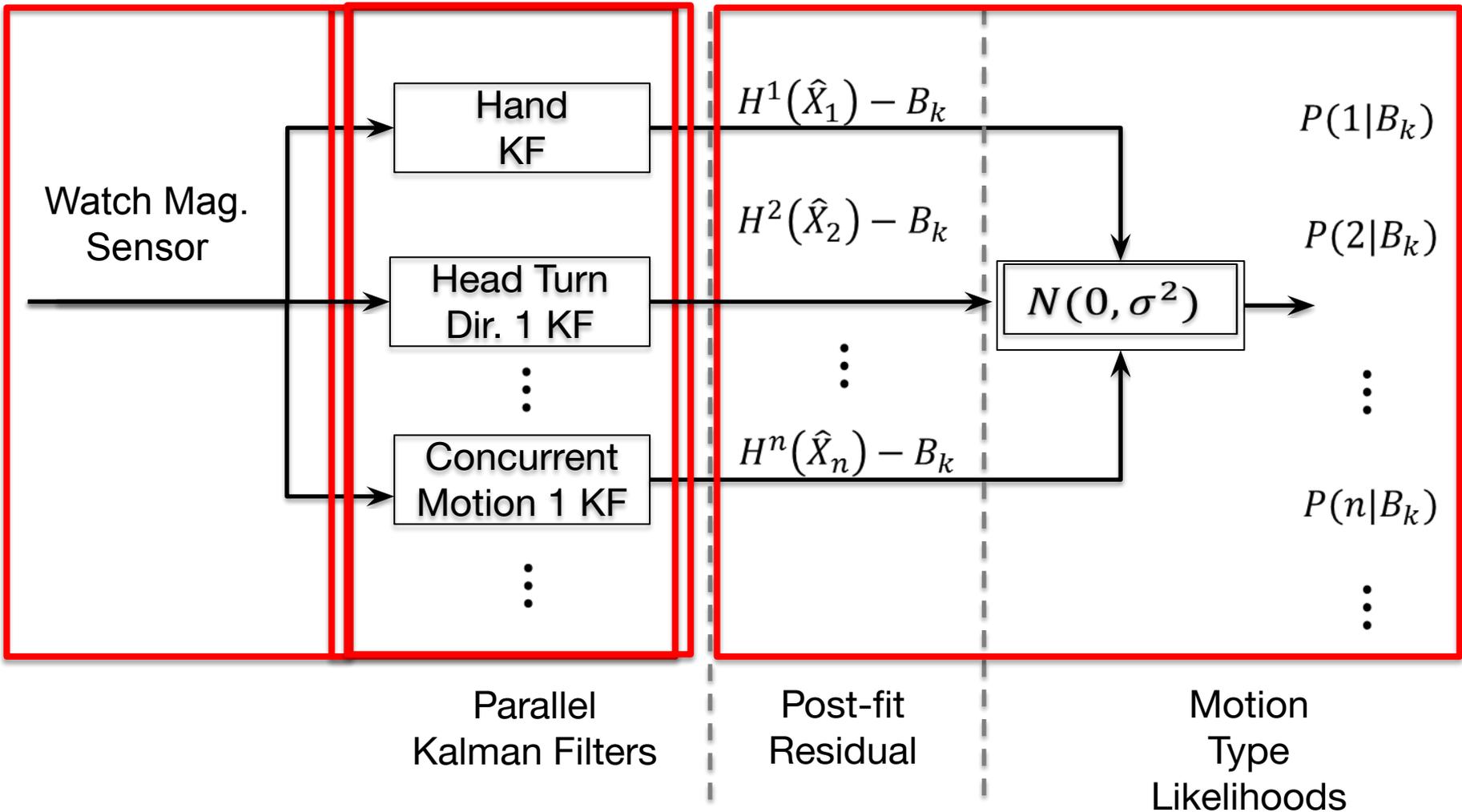
Underdetermined system

Observation:  
Motion constraints  
while following  
guidelines





# Simultaneous Tracking and Classification (STC) Algorithm





## State Transition Model:

$$\begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix} \rightarrow X_{k+1} = F \cdot X_k$$

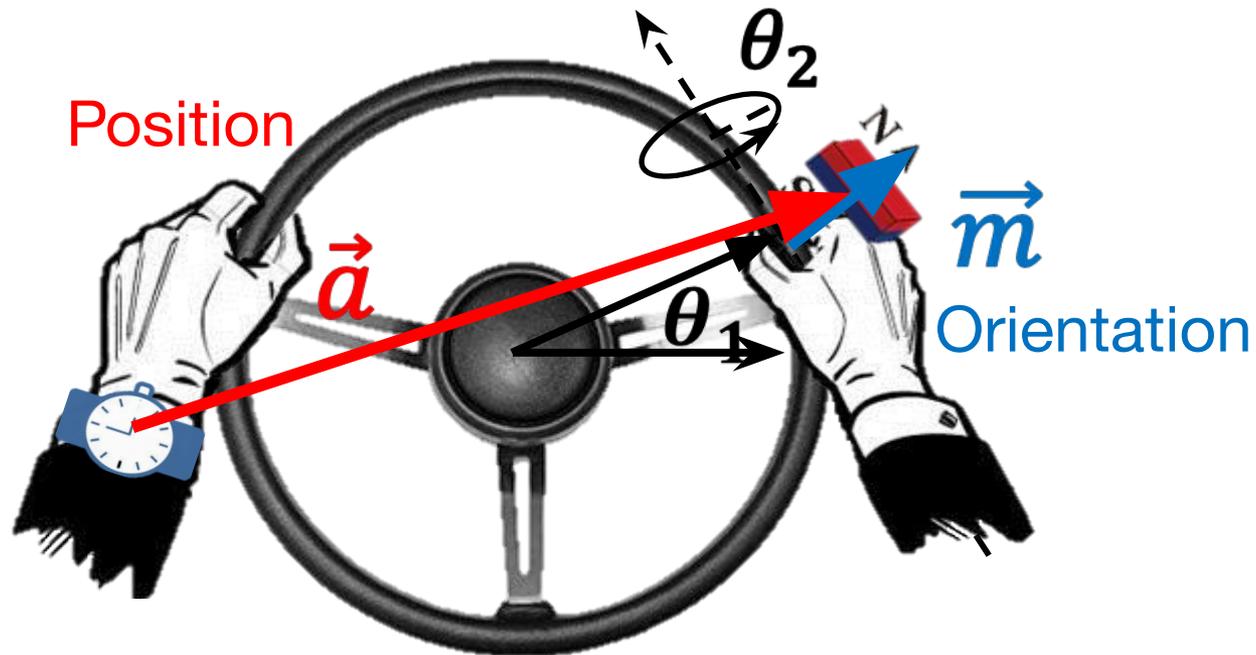
State Transition Matrix

## Sensor Measurement Model:

$$\begin{bmatrix} b_x \\ b_y \\ b_z \end{bmatrix} \rightarrow B_k = H(X_k)$$



# Hand Motion Kalman Filter

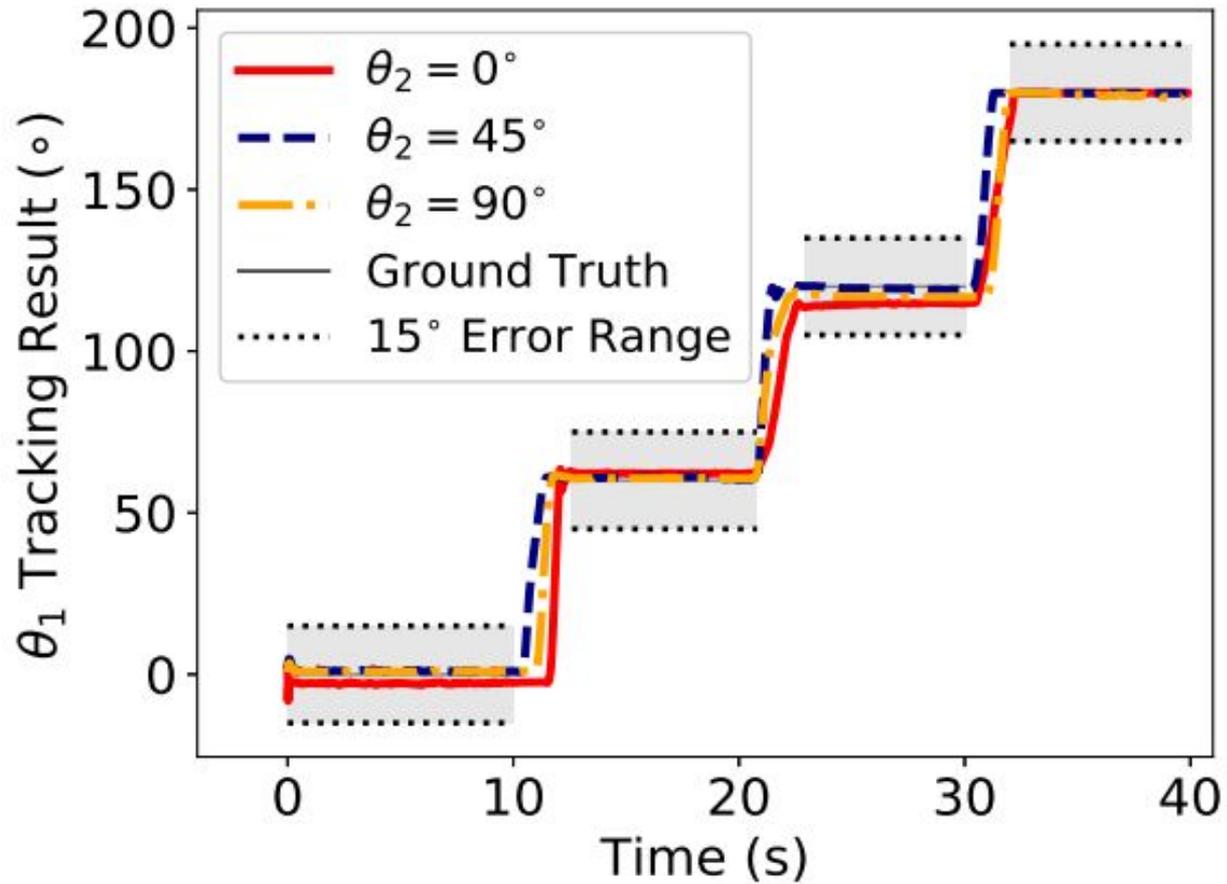


$KF^S$ :

$$X^S_{k+1} = F^S \cdot X^S_k$$
$$B_k = H^S(\theta_1, \theta_2) = \frac{\mu}{4\pi |\vec{a}|^3} \left[ \frac{3\vec{a} \cdot \vec{a}^T}{|\vec{a}|^2} - \mathbf{I} \right] \vec{m}$$



# Hand Tracking Results





Divide into left, right and down turns

- Head turn angle  $\gamma_k$  in the state variable
- Linear approximation for measurement model

$$KF^l: \quad X^l_{k+1} = F^l \cdot X^l_k$$
$$B_k \approx H^l(\gamma_k) = \vec{a}_0 + \vec{a}_1 * \gamma_k$$

Linear approximation



## State Transition Model:

- Include both hand and head angles
- Limit the state variables to large values

## Measurement Model:

- Sum of hand and head measurement models

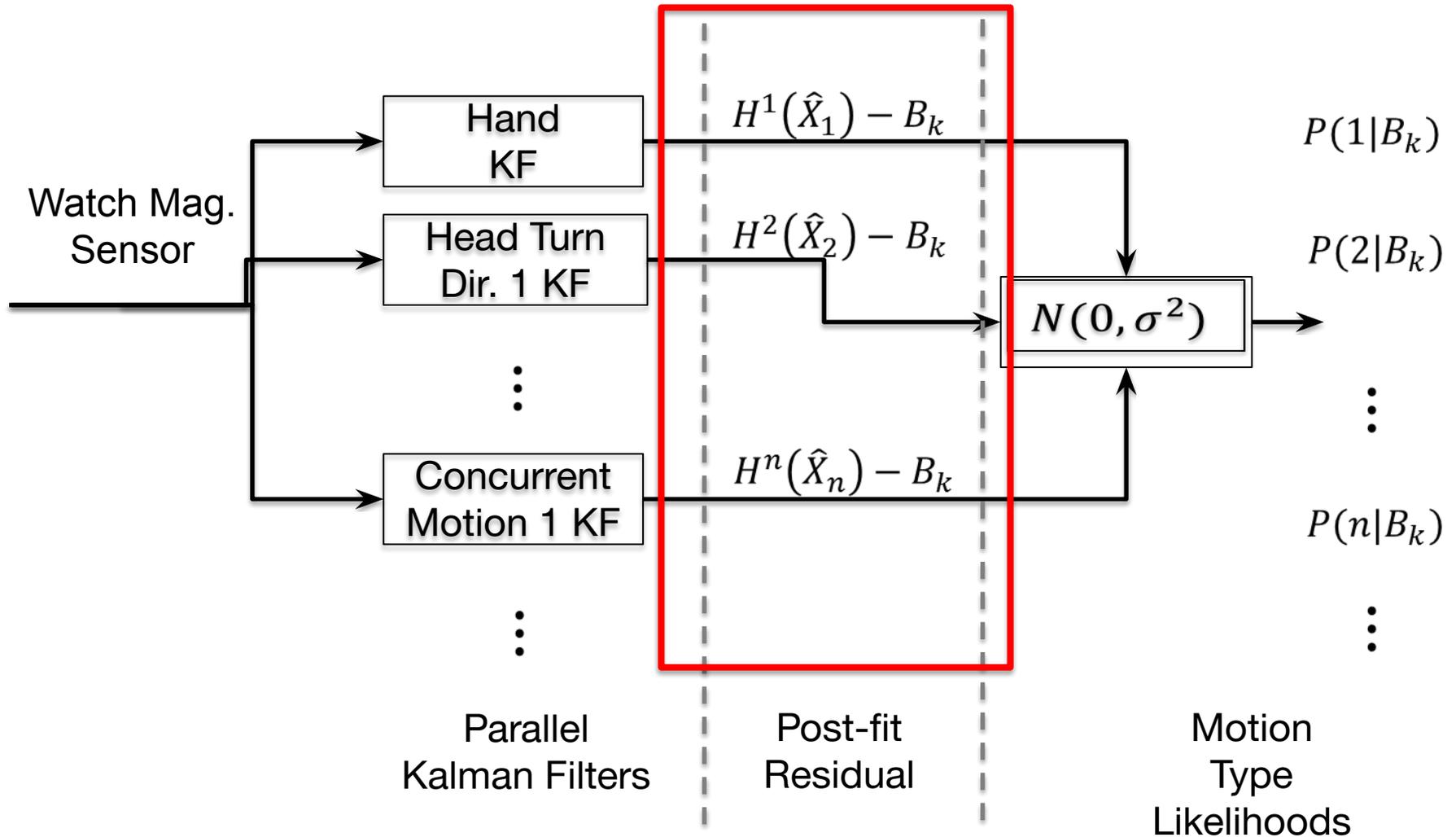
Hand Measurement

Head Measurement

$$\begin{aligned}
 KF^{sl}: \quad X^{sl}_{k+1} &= F^{sl} \cdot X^{sl}_k \\
 B_k &= H^{sl}(\theta_{1k}, \theta_{2k}, \gamma_k) \\
 &= H^s(\theta_{1k}, \theta_{2k}) + H^l(\gamma_k)
 \end{aligned}$$

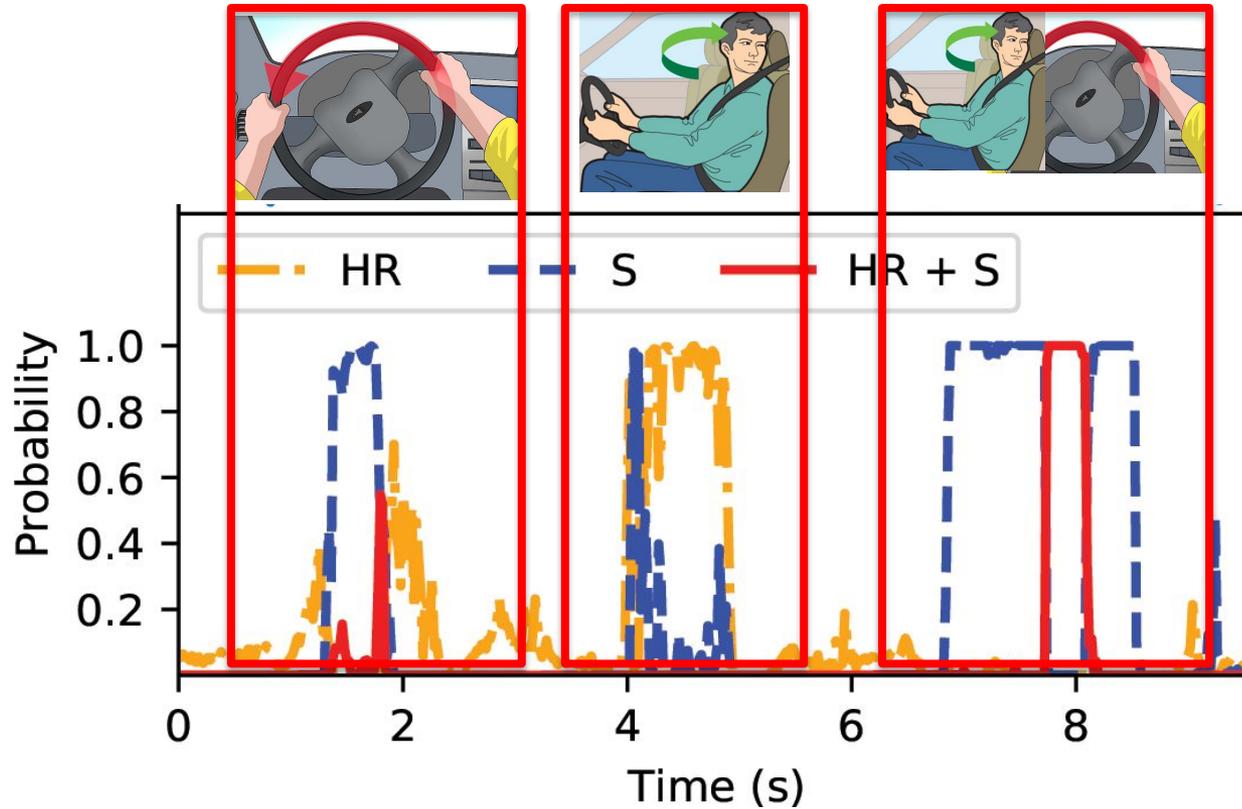


# Simultaneous Tracking and Classification (STC) Algorithm





# Motion Type Recognition



S: Steering

HR: Head Right turn

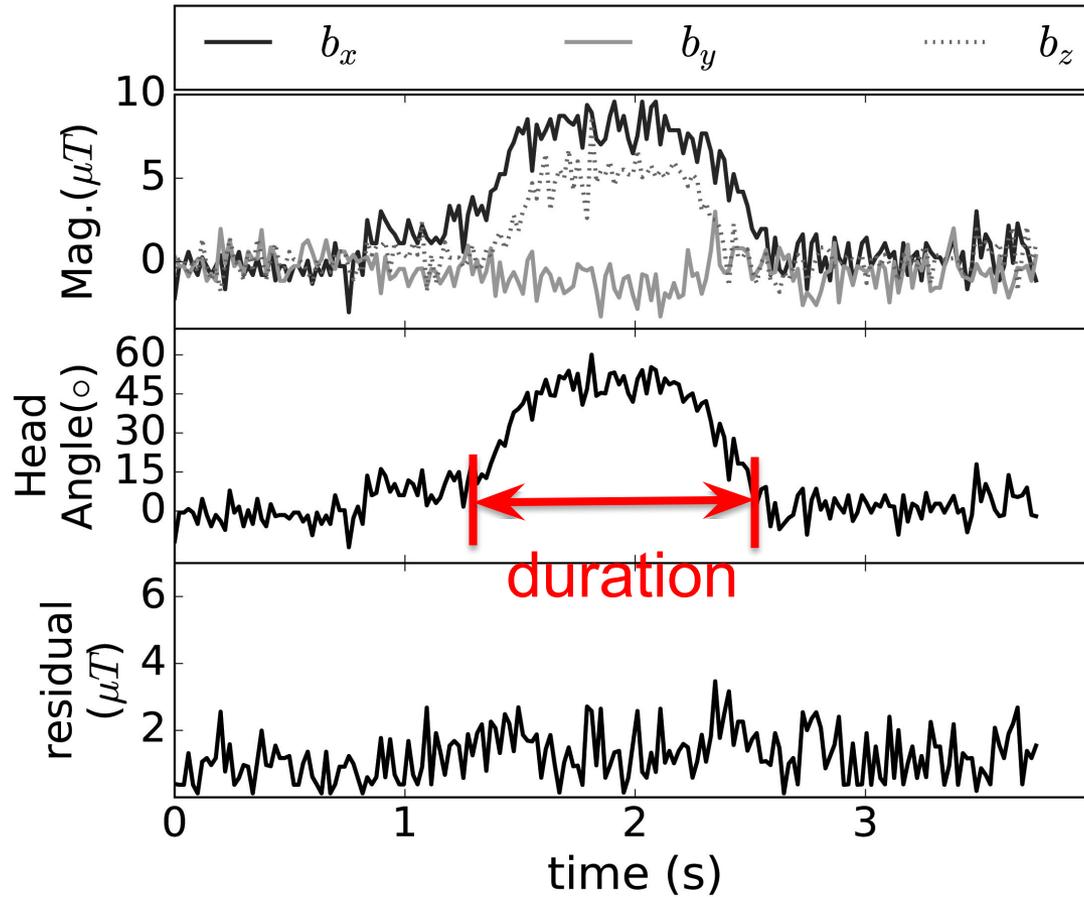
HR+S: concurrent motion



# Safe Driving Monitoring

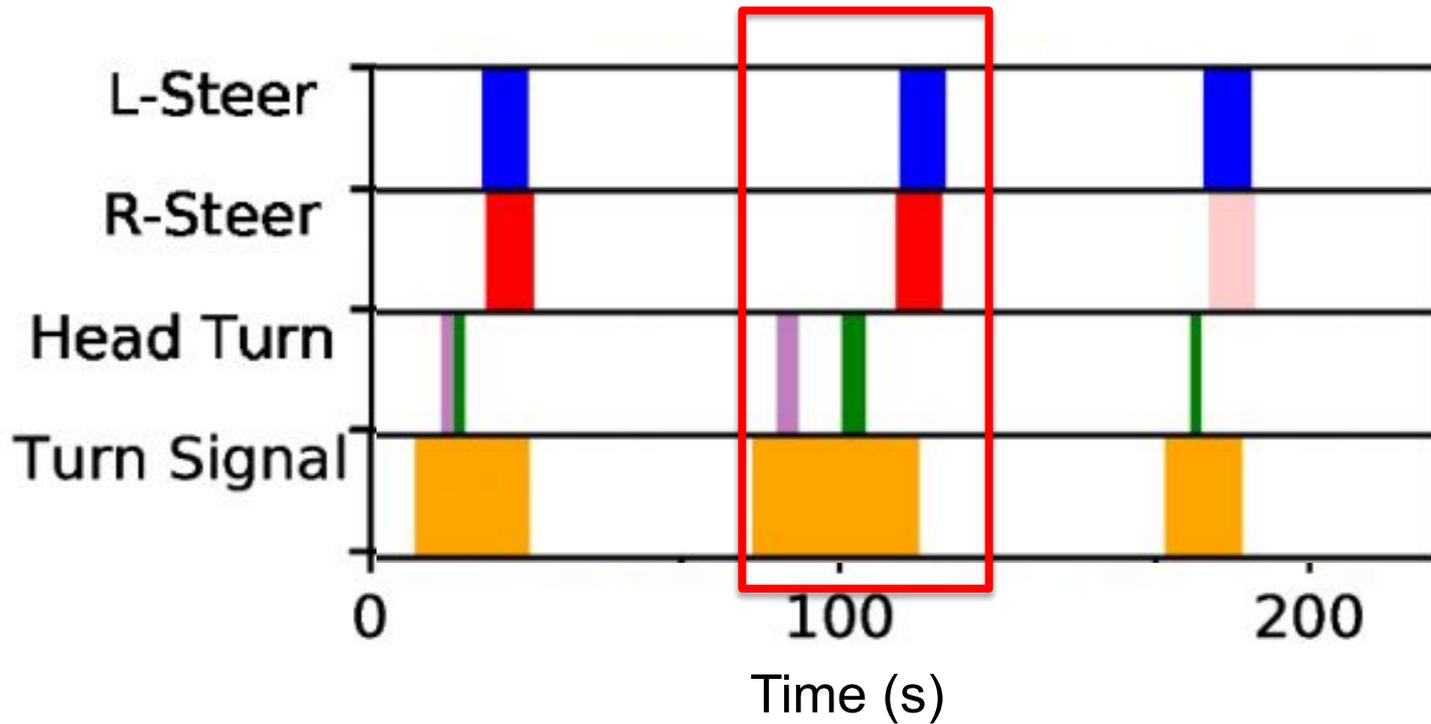


# Visual Distraction Detection



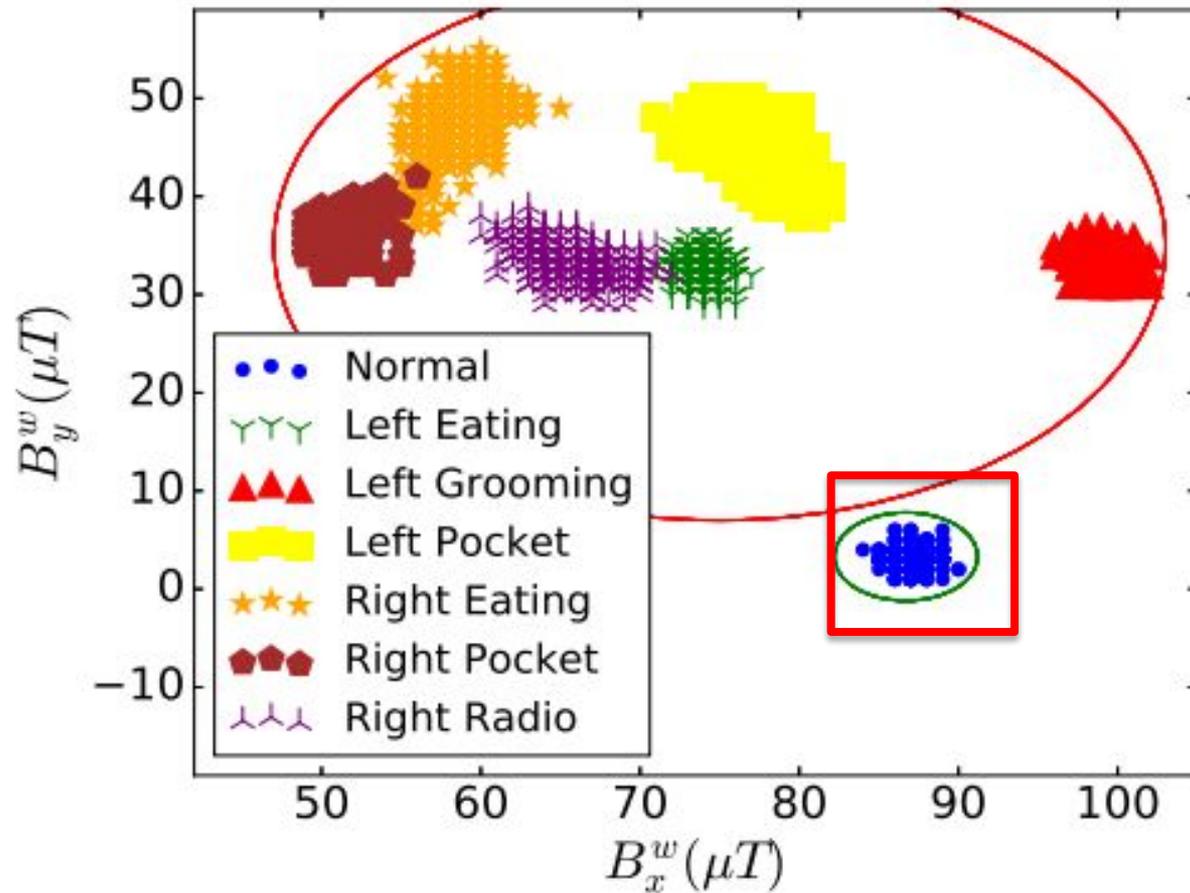


# Safe Steering Monitoring





# Manual Distraction Detection





# Evaluation



# Evaluation: Motion Type Classification



	OW	0.96	0.02	0.01				
	LS	0.06	0.91	0.01	0.01			
Right hand Steer (RS)	RS	0.02	0.88	0.04		0.03	0.04	
Head Down turn (HD)	HD		0.02	0.97	0.01			
Head Left turn (HL)	HL		0.03		0.97			
Head Right turn (HR)	HR		0.07		0.01	0.92		
concurrent motion (S+H)	S+H		0.12				0.88	
		OW	LS	RS	HD	HL	HR	S+H
		Predicted label						

Driving Motion Type Confusion Matrix



- 10 drivers, 500+ minutes road test
- IRB approved
- Co-pilot records ground truth
- 547 driving events, including distraction, steering, and head turn motions.
- User survey for experience



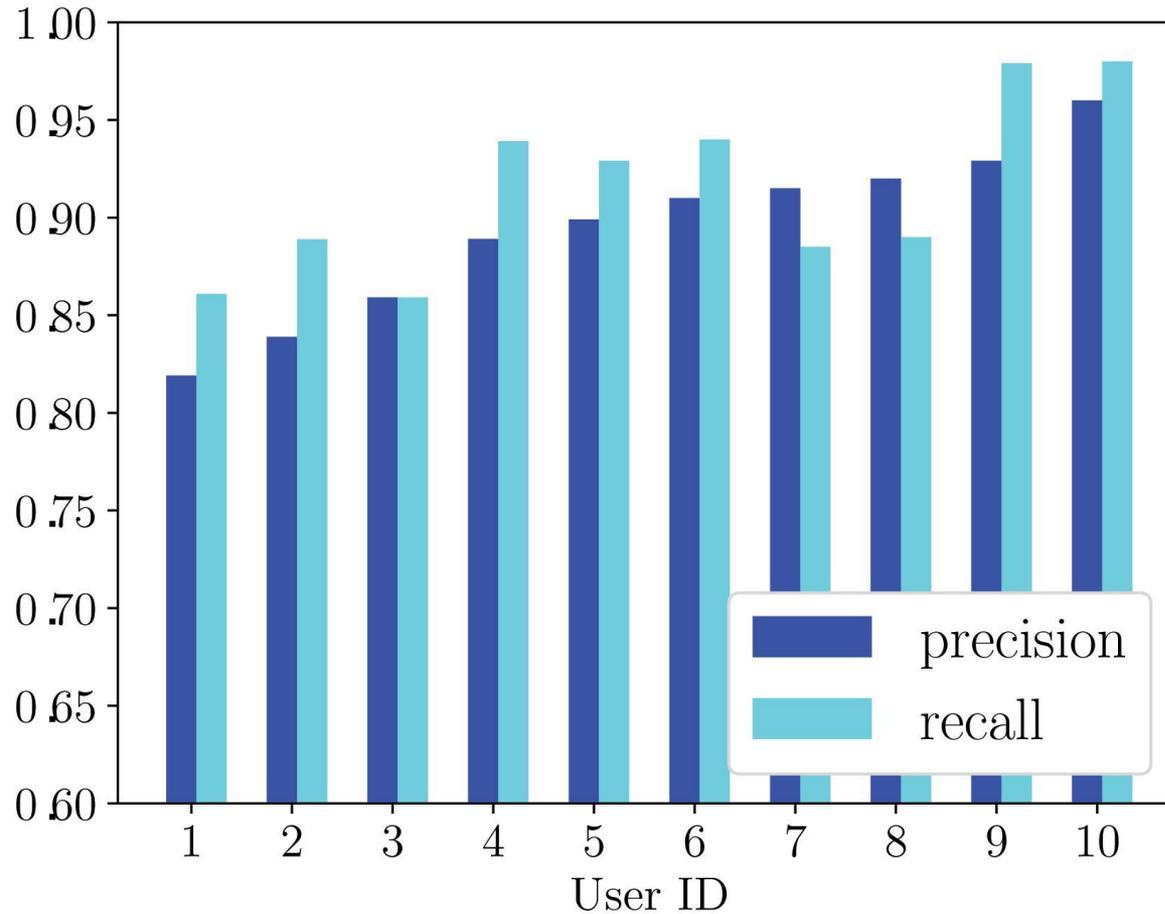
# Unsafe Driving Detection



Events	Precision	Recall
Unsafe Turning	87%	84%
Manual Distraction	92%	89%
Visual Distraction	85%	91%
Overall	87%	90%



# Unsafe Driving Detection

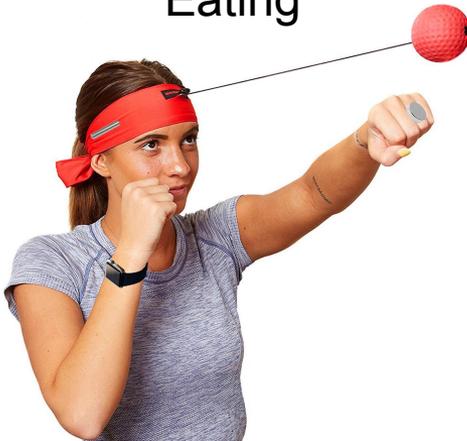




Eating



Hand Washing



Hand Head Coordination Exercise



Cycling



- MagTrack: A system that monitors two-hand and head motions for many driving activities
- Use magnetic tags to track constrained motions with high accuracy
- A novel algorithm that tracks two magnets with a single sensor
- Achieves 88.5% of unsafe driving detection accuracy in road tests with 10 users, with 500+ events



# Q&A for MagTrack

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